Proving Differential Privacy via Probabilistic Couplings

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A new approach to formulating privacy goals: the risk to one's privacy, or in general, any type of risk ... should not substantially increase as a result of participating in a statistical database.

This is captured by differential privacy.

- Cynthia Dwork

Increasing interest

In research...



Increasing interest

In research...



... and in the "real world"





Dwork, McSherry, Nissim, and Smith

Let $\epsilon \ge 0$ be a parameter, and suppose there is a binary adjacency relation Adj on D. A randomized algorithm $M : D \to \mathbf{Distr}(R)$ is ϵ -differentially private if for every set of outputs $S \subseteq R$ and every pair of adjacent inputs d_1, d_2 , we have

$$\Pr_{x \sim M(d_1)}[x \in S] \leq \exp(\epsilon) \cdot \Pr_{x \sim M(d_2)}[x \in S]$$

Composition properties



Whole program is 2ϵ -private

Composition properties



Whole program is 2ϵ -private

Formally ...

Consider randomized algorithms $M : D \rightarrow \text{Distr}(R)$ and $M : R \rightarrow D \rightarrow \text{Distr}(R')$. If M is ϵ -private and for every $r \in R$, M'(r) is ϵ' -private, then the composition is $(\epsilon + \epsilon')$ -private:

$$r \stackrel{\hspace{0.1em}{\scriptstyle{\scriptstyle{\circ}}}}{\scriptstyle{\scriptstyle{\leftarrow}}} M(d); res \stackrel{\hspace{0.1em}{\scriptstyle{\scriptstyle{\circ}}}}{\scriptstyle{\scriptstyle{\leftarrow}}} M(r,d); \operatorname{return}(res)$$

Differential privacy is a:

relational property of probabilistic programs.

When privacy follows from composition...



When privacy follows from composition...



(Linear types, refinement types, self products, relational Hoare logics, \dots)

When privacy doesn't follow from composition...



When privacy doesn't follow from composition...



How to formally verify?

Use approximate coupling view of privacy to extend the logic apRHL

Combine smaller, pointwise proofs to prove differential privacy in apRHL

Get new, much simpler proofs using coupling composition principle

Imperative language with sampling

$$x \leftarrow \mathcal{L}_{\epsilon}(e)$$

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approximate probabilistic Relational Hoare Logic

$$\vdash \{\Phi\} \ c_1 \sim_{\epsilon} c_2 \ \{\Psi\}$$

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Non-probablistic

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Numeric index

Definition

Let $R \subseteq A \times A$ be a relation and $\epsilon \ge 0$. Two distributions $\mu_1, \mu_2 \in \mathbf{Distr}(A)$ are related by the ϵ -approximate lifting of R if there exists $\mu_L, \mu_R \in \mathbf{Distr}(A \times A)$ with:

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- $\pi_1(\mu_L) = \mu_1$ and $\pi_2(\mu_R) = \mu_2$;
- for every $S \subseteq A \times A$,

 $\Pr_{z \sim \mu_L}[z \in S] \leq \exp(\epsilon) \cdot \Pr_{z \sim \mu_R}[z \in S]$

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- for every $S \subseteq A \times A$,

 $\Pr_{z \sim \mu_L}[z \in S] \leq \exp(\epsilon) \cdot \Pr_{z \sim \mu_R}[z \in S]$

Write:
$$\mu_1 R^{\sharp \epsilon} \mu_2$$

Interpreting judgments

$\vdash \{\Phi\} \ c_1 \sim_{\epsilon} c_2 \ \{\Psi\}$

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Memories related by Φ

Interpreting judgments

 $\vdash \{\Phi\} \ c_1 \sim_{\epsilon} c_2 \ \{\Psi\}$

Memories related by Φ \Downarrow

Distributions related by $\Psi^{\sharp\epsilon}$

Differential privacy in apRHL

$\vdash \{Adj(d_1, d_2)\} \ c \sim_{\epsilon} c \ \{res_1 = res_2\}$

Differential privacy in apRHL

$\vdash \{ Adj(d_1, d_2) \} c \sim_{\epsilon} c \{ res_1 = res_2 \}$ Exactly ϵ -differential privacy

Proof system

Proof system

 $\vdash \{\Psi \{e_1 \langle 1 \rangle, e_2 \langle 2 \rangle / x_1 \langle 1 \rangle, x_2 \langle 2 \rangle \}\} \ x_1 \leftarrow e_1 \sim_0 x_2 \leftarrow e_2 \ \{\Psi\}[\text{ASSN}]$

$$\begin{split} & \frac{\left|\left\{\left|e_{1}-e_{2}\right|\leq k\right\} x_{1} \notin \mathcal{L}_{\epsilon}(e_{1})\sim_{k\cdot\epsilon} x_{2} \notin \mathcal{L}_{\epsilon}(e_{2}) \left\{x_{1}=x_{2}\right\}^{\left[\mathsf{LAP}\right]}}{\left|\left\{\Phi\right\} c_{1}\sim_{\epsilon} c_{2} \left\{\Psi'\right\} \quad \vdash \left\{\Psi'\right\} c_{1}'\sim_{\epsilon'} c_{2}' \left\{\Psi\right\}} [\mathsf{SEQ}] \\ & \frac{\left|\left\{\Phi\right\} c_{1}\right\} c_{1}\sim_{\epsilon} c_{2} \left\{\Psi'\right\} \quad \vdash \left\{\Phi\land b_{1}(1)\right\} c_{1}\sim_{\epsilon} c_{2} \left\{\Psi\right\} \quad \vdash \left\{\Phi\land b_{1}(1)\right\} c_{1}\sim_{\epsilon} c_{2} \left\{\Psi\right\}}{\left|\left\{\Phi\land b_{1}(1)=b_{2}(2)\right\}\right\} \text{ if } b_{1} \text{ then } c_{1} \text{ else } d_{1}\sim_{\epsilon} \text{ if } b_{2} \text{ then } c_{2} \text{ else } d_{2} \left\{\Psi\right\}} [\mathsf{COND}] \\ & \frac{\left|\left\{\Theta\land b_{1}(1)\Rightarrow b_{2}(2)\land k=e(1)\land e(1)\leq n\right\} c_{1}\sim_{\epsilon_{k}} c_{2} \left\{\Theta\land b_{1}(1)=b_{2}(2)\land k$$

(Laplace) Sampling rule

$$\frac{1}{\vdash \{|e_1 - e_2| \leq \mathbf{k}\}} x_1 \stackrel{\text{\tiny{(1)}}}{\to} \mathcal{L}_{\epsilon}(e_1) \sim_{\mathbf{k} \cdot \epsilon} x_2 \stackrel{\text{\tiny{(1)}}}{\to} \mathcal{L}_{\epsilon}(e_2) \{x_1 = x_2\}} L_{\mathrm{AP}}$$

(Laplace) Sampling rule

$$\frac{1}{\vdash \{|e_1 - e_2| \leq \mathbf{k}\}} x_1 \stackrel{\text{\tiny (1)}}{\leftarrow} \mathcal{L}_{\epsilon}(e_1) \sim_{\mathbf{k} \cdot \epsilon} x_2 \stackrel{\text{\tiny (2)}}{\leftarrow} \mathcal{L}_{\epsilon}(e_2) \{x_1 = x_2\}} LAP$$

"Pay" distance between centers ↓ Assume samples are equal

Sequence rule

$$\frac{\vdash \{\Phi\} \ c_1 \sim_{\epsilon} c_2 \ \{\Theta\} \ \vdash \{\Theta\} \ c_1' \sim_{\epsilon'} c_2' \ \{\Psi\}}{\vdash \{\Phi\} \ c_1; c_1' \sim_{\epsilon+\epsilon'} c_2; c_2' \ \{\Psi\}} \operatorname{Seq}$$

Generalizes privacy composition

• Θ , Ψ assert equality on outputs

Sequence rule

$$\frac{\vdash \{\Phi\} \ c_1 \sim_{\epsilon} c_2 \ \{\Theta\} \ \vdash \{\Theta\} \ c'_1 \sim_{\epsilon'} c'_2 \ \{\Psi\}}{\vdash \{\Phi\} \ c_1; c'_1 \sim_{\epsilon+\epsilon'} c_2; c'_2 \ \{\Psi\}} \operatorname{Seq}$$

Generalizes privacy composition

• Θ , Ψ assert equality on outputs

"Costs" sum up

Assume "paid" facts in rest of program

The coupling perspective

Approximate liftings are approximate versions of probabilistic couplings The coupling perspective

Approximate liftings are approximate versions of probabilistic couplings

New liftings \iff New proof rules

New sampling rule: [LAPNULL]

 $\frac{x_1 \notin FV(e_1), x_2 \notin FV(e_2)}{\vdash \{\top\} \ x_1 \not \leftarrow \mathcal{L}_{\epsilon}(e_1) \sim_{\mathbf{0}} x_2 \not \leftarrow \mathcal{L}_{\epsilon}(e_2) \ \{x_1 - x_2 = e_1 - e_2\}}$

New sampling rule: [LAPNULL]

$$\begin{array}{c} x_1 \notin \mathsf{FV}(e_1), x_2 \notin \mathsf{FV}(e_2) \\ \hline \vdash \{\top\} \hspace{0.1cm} x_1 \twoheadleftarrow \mathcal{L}_\epsilon(e_1) \sim_{\mathbf{0}} x_2 \twoheadleftarrow \mathcal{L}_\epsilon(e_2) \hspace{0.1cm} \{x_1 - x_2 = e_1 - e_2\} \end{array}$$

New sampling rule: [LAPGEN]

 $x_1 \notin FV(e_1), x_2 \notin FV(e_2)$

 $\overline{\vdash \{|e_1 - (e_2 + s)| \le k\}} \quad x_1 \notin \mathcal{L}_{\epsilon}(e_1) \sim_{\mathbf{k} \cdot \epsilon} x_2 \notin \mathcal{L}_{\epsilon}(e_2) \quad \{x_1 = x_2 + s\}$

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"Pay" distance to shift centers ↓ Assume shifted samples

New lifting principle: combining pointwise liftings

$$\frac{\text{for all } v, \quad \vdash \{\Phi\} \ c_1 \sim_{\epsilon} c_2 \ \{(e_1 = v) \rightarrow (e_2 = v)\}}{\vdash \{\Phi\} \ c_1 \sim_{\epsilon} c_2 \ \{e_1 = e_2\}} \text{ PW-Eq}$$

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Separate proofs for each output

New lifting principle: combining pointwise liftings

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Leibniz equality

$$(orall v, (e_1=v)
ightarrow (e_2=v))
ightarrow e_1=e_2$$

Internalizing a universal quantifier

- ► Not sound in general
- Sound for certain equality predicates

∀ values, ∃ a lifting such that ... ↓ ∃ a lifting such that ∀ values, ...

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Putting it all together



Please see the paper!

A brief preview: the Above Threshold algorithm

```
\begin{array}{l} \mathcal{AT}(t,d) = \{ \\ i \leftarrow 1; x \leftarrow 0; \\ \tilde{t} \leftarrow \mathcal{L}_{\epsilon/2}(t); \\ \text{while } i \leq k \text{ do} \\ s \leftarrow \mathcal{L}_{\epsilon/4}(q[i](d)); \\ \text{ if } (s \geq \tilde{t} \ \land x = 0) \text{ then } x \leftarrow i; \\ i \leftarrow i + 1; \\ \text{ return } x \\ \} \end{array}
```

A brief preview: the Above Threshold algorithm

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Standard composition: AT(t, -) is ke-private

A brief preview: the Above Threshold algorithm

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Standard composition: AT(t, -) is ke-private

In fact: AT(t, -) is ϵ -private

Complicated privacy proof(s)

3.1 Privacy Proof for Algorithm 1

We now prove the privacy of AlgorithmIII We break the proof down into two steps, to make the proof easier to understand, and, more importantly, to point out what confusions likely caused the different non-private variants of SVT to be proposed. In the first step, we analyze the situation where the output is J_{i}^{*} , a length- ℓ vector $(\bot_{i}, \cdots, \bot_{i})$, indicating that all ℓ queries are tested to be below the threshold.

LEMMA 1. Let A be Algorithm []. For any neighboring datasets D and D', and any integer ℓ , we have

$$\Pr[A(D) = \perp^{\ell}] \le e^{\frac{1}{2}} \Pr[A(D') = \perp^{\ell}]$$

PROOF. We have

$$\begin{split} &\Pr\left[\mathcal{A}(D) = \bot^{\ell}\right] = \int_{-\infty}^{\infty} f_{\bot}(D, z, L) \, \mathrm{d}z, \\ &\text{where } f_{\bot}(D, z, L) = \Pr[p = z] \prod_{i \in L} \Pr[q_i(D) + \nu_i < T_i + z], \quad (\mathrm{I} \\ &\text{ and } L = \{1, 2, \cdots, \ell\}. \end{split}$$

The probability of outputting \perp^ℓ over D is the summation (or integral) of terms $f_\perp(D,z,L)$, each of which is the product of $\Pr\{p=z\}$, the probability that the threshold noise equals z, and $\prod_i \Pr[q_i(D) + \nu_i < T_i + z]$, the conditional probability that \perp^ℓ

^{10.1} is the output on D given that the threshold noise ρ is z. (Note that given D, T, the queries, and ρ , whether one query results in \perp or not depends completely on the noise ν_i and is independent from whether any other query results in \perp .) If we can prove

$$f_{\perp}(D, z, L) \le e^{\frac{1}{2}} f_{\perp}(D', z + \Delta, L),$$
 (2)

then we have

$$\begin{split} \left[\mathcal{A}(D) = \bot^{\ell}\right] &= \int_{-\infty}^{\infty} f_{\perp}(D, s, L) \, ds \\ &\leq \int_{-\infty}^{\infty} \delta^{2} f_{\perp}(D', s + \Delta, L) \, ds \quad \text{from (2)} \\ &= e^{\frac{1}{2}} \int_{-\infty}^{\infty} f_{\perp}(D', z', L) \, dz' \quad \text{ist } z' = z + \\ &= e^{\frac{1}{2}} \Pr\left[\mathcal{A}(D') = \bot^{\ell}\right]. \end{split}$$

This proves the lemma. It remains to prove Eq.(2). For any query q_i , because $|q_i(D)-q_i(D')| \le \Delta$ and thus $-q_i(D) \le \Delta - q_i(D')$, we have

 $Pr[q_i(D) + \nu_i < T_i + s] = Pr[\nu_i < T_i - q_i(D) + s]$ $\leq Pt[\nu_i < T_i + \Delta - q_i(D') + s]$ $= Pt[q_i(D') + \nu_i < T_i + (s + \Delta)]$ (3)

With (3), we prove (2) as follows:

$$\begin{split} f_{\perp}(D, z, L) &= \mathsf{Pr}[\rho = z) \prod_{i \in L} \mathsf{Pr}[q_i(D) + \nu_i < T_i + z] \\ &\leq e^{\frac{1}{2}} \mathsf{Pr}[\rho = z + \Delta] \prod_{i \in L} \mathsf{Pr}[q_i(D') + \nu_i < T_i + (z + \Delta)] \\ &= e^{\frac{1}{2}} f_{\perp}(D', z + \Delta, L). \end{split}$$

0

That is, by using a noisy threshold, we are able to bound the probability ratio for all the negative query answers (i.e., $\perp's)$ by $e^{\frac{1}{2}}$, no matter how many negative answers there are.

We can obtain a similar result for positive query answers in the same way.

Let
$$f_{\top}(D, z, L) = \Pr[\rho = z] \prod_{i \in L} \Pr[q_i(D) + v_i \ge T_i + z]$$

We have $f_{\top}(D, z, L) \le e^{\frac{C}{2}} f_{\top}(D', z - \Delta, L)$, and thus
 $\Pr[\mathcal{A}(D) = \top^{\ell}] \le e^{\frac{C}{2}} \Pr[\mathcal{A}(D') = \top^{\ell}]$.

This likely contributes to the misunderstandings behind Algorithms [$\frac{2}{3}$ and $\frac{6}{6}$, which treat positive and negative answers exactly the same way. The problem is that while one is free to choose to bound positive or negative side, one cannot bound both.

We also observe that the proof of Lemma [][will go through if no noise is added to the query answers, i.e., $\mu_i = 0$. Because Eq (3) holds even when $\nu_i = 0$. It is likely because of this observation that Algorithm[5] adds no noise to query answers. However, when considering ourcomes that include so tho positive answers (T's) and negative answers (1-5), one has to add noises to the query answers, as we show below.

THEOREM 2. Algorithm lis e-DP.

PROOF. Consider any output vector $a \in \{\bot, \top\}^{\ell}$. Let $a = \langle a_1, \cdots, a_{\ell} \rangle$, $\mathbf{1}^{n}_{+} = \{i : a_i = \top\}$, and $\mathbf{1}^{n}_{\perp} = \{i : a_i = \bot\}$. Clearly, $|\mathbf{1}^{n}_{+}| \leq c$. We have

$$Pr[A(D) = a] = \int_{-\infty}^{\infty} g(D, z) dz$$
, where
 $g(D, z) = Pr[p = z] \prod_{i \in I} Pr[q_i(D) + \nu_i < T_i + z] \prod_{i \in I} Pr[q_i(D) + \nu_i \ge T_i + z]$

We want to show that $g(D, z) \le e^{\epsilon}g(D', z+\Delta)$. This suffices to prove that $\Pr[\mathcal{A}(D) = a] \le e^{\epsilon}\Pr[\mathcal{A}(D') = a]$. Note that g(D, z) can be written as:

$$g(D, s) = f_{\perp}(D, s, \mathbf{I}^{\mathbf{0}}_{\perp}) \prod_{i \in \mathbf{I}^{\mathbf{0}}_{i}} Pr[q_{i}(D) + \nu_{i} \ge T_{i} + s$$

Following the proof of Lemma], we can show that $f_{\perp}(D, s, \mathbf{I}_{\perp}^{0}) \le e^{\frac{1}{2}} f_{\perp}(D', z + \Delta, \mathbf{I}_{\perp}^{0})$, and it remains to show

$$\prod_{i \in \mathbb{Z}^{\frac{n}{2}}} \Pr[q_i(D) + \nu_i \ge T_i + z] \le e^{\frac{L}{2}} \prod_{i \in \mathbb{Z}^{\frac{n}{2}}} \Pr[q_i(D') + \nu_i \ge T_i + z + \Delta].$$
(4)

Because $\nu_i = \text{Lap}\left(\frac{de\Delta}{r}\right)$ and $|q_i(D) - q_i(D')| \le \Delta$, we have

$$Pr[q_i(D) + \nu_i \ge T_i + z] = Pr[\nu_i \ge T_i + z - q_i(D)]$$

$$\leq Pr[\nu_i \ge T_i + z - \Delta - q_i(D')] \quad (5)$$

$$\leq e^{\frac{1}{N}} Pr[\nu_i \ge T_i + z - \Delta - q_i(D') + 2\Delta] \quad (6)$$

$$= e^{\frac{1}{N}} Pr[q_i(D') + \nu_i \ge T_i + z + \Delta].$$

Eq (5) is because $-q_i(D') \ge -\Delta - q_i(D')$, and Eq (6) is from the Laplace distribution's property. This proves Eq (4). \Box

The basic idea of the proof is that when comparing g(D, z) with $g(D', z + \Delta)$, we can bound the probability ratio for all outputs of \bot to no more than $e^{-1}b$ youing a noisy threshold, no matter how many such outputs there are. To bound the ratio for the \top outputs to no more than e^{+1} , we need to add sufficient Laplacian noises, which should scale with c, the number of nositive outputs.

Now we turn to Algorithms 316 to clarify what are wrong with their privacy proofs and to give their DP properties.

— Lyu, Su, Dong

Many slightly different versions

Figure 1: A Selection of SVT Variants

Input/Output shared by all SVT Algorithms

Input: A private database D_i a stream of queries $Q = q_1, q_2, \cdots$ each with sensitivity no more than Δ_i either a sequence of thresholds $T = T_1, T_2, \cdots$ or a single threshold T (see footnote '), and c_i the maximum number of queries to be answered with T_i output: A stream of answers a_1, a_2, \cdots , where each $a_i \in \{T_i, \bot\}$ U and R denotes the set of all real numbers.

Algorithm 1 An instantiation of the SVT proposed in this paper.	Algorithm 2 SVT in Dwork and Roth 2014 [8].
Input: $D, Q, \Delta, T = T_1, T_2, \cdots, c$.	Input: D, Q, Δ, T, c .
1: $\rho = \text{Lap}\left(\frac{2\Delta}{2}\right)$, count = 0	1: $\rho = \text{Lap}\left(\frac{2n\Delta}{n}\right)$, count = 0
2: for each query $q_i \in Q$ do	2: for each query $q_i \in Q$ do
3: $\nu_i = Lap\left(\frac{4c\Delta}{c}\right)$	3: $\nu_i = Lap\left(\frac{4c\Delta}{c}\right)$
4: If $q_i(D) + \nu_i \ge T_i + \rho$ then	4: if $q_i(D) + \nu_i \ge T + \rho$ then
5: Output $a_i = \top$	5: Output $a_i = \top, \rho = Lap\left(\frac{2c\Delta}{c}\right)$
6: count = count + 1, Abort if count ≥ c.	6: count = count + 1, Abort if count ≥ c.
7: else	7: else
 Output a_i = ⊥ 	 Output a_i = ⊥
9: end if	9: end if
10: end for	10: end for
Algorithm 3 SVT in Roth's 2011 Lecture Notes [15].	Algorithm 4 SVT in Lee and Clifton 2014 [13].
Input: D, Q, Δ, T, c .	Input: D, Q, Δ, T, c .

input: D, Q, Δ, I, c .	input: D, Q, Δ, I, c .
1: $\rho = \text{Lap}\left(\frac{2\Delta}{r}\right)$, count = 0	1: $\rho = \text{Lap}\left(\frac{4\Delta}{r}\right)$, count = 0
2: for each query $q_i \in Q$ do	 for each query q_i ∈ Q do
3: $\nu_i = Lap\left(\frac{2c\Delta}{c}\right)$	3: $\nu_i = Lap\left(\frac{4\Delta}{\lambda_i}\right)$
4: if $q_i(D) + \nu_i \ge T + \rho$ then	4: if $q_i(D) + \nu_i \ge T + \rho$ then
5: Output $a_i = q_i(D) + \nu_i$	 Output a_i = ⊤
 count = count + 1, Abort if count ≥ c. 	6: count = count + 1, Abort if count ≥ c.
7: else	7: else
 Output a_i = ⊥ 	8: Output $a_i = \bot$
9: end if	9: end if
10: end for	10: end for

Algorithm 5 SVT in Stoddard et al. 2014 [18].	Algorithm 6 SVT in Chen et al. 2015 [1].
Input: D, Q, Δ, T .	Input: $D, Q, \Delta, T = T_1, T_2, \cdots$.
1: $\rho = Lap\left(\frac{2\Delta}{\epsilon}\right)$	1: $\rho = \text{Lap}\left(\frac{2\Delta}{\epsilon}\right)$
2: for each query $q_i \in Q$ do	 for each query q_i ∈ Q do
3: $\nu_i = 0$	3: $\nu_i = \text{Lap}\left(\frac{2\Delta}{\epsilon}\right)$
4: if $q_i(D) + \nu_i \ge T + \rho$ then	4: if $q_i(D) + \nu_i \ge T_i + \rho$ then
5: Output $a_i = \top$	 Output a_i = ⊤
6:	6:
7: else	7: else
8: Output $a_i = \bot$	8: Output $a_i = \bot$
9: end if	9: end if
10: end for	10: end for

	Alg.1	Alg. 2	Alg. 3	Alg.4	Alg. 5	Alg. 6
Scale of threshold noise ρ	$2\Delta/\epsilon$	$2c\Delta/\epsilon$	$2\Delta/\epsilon$	$4\Delta/\epsilon$	$2\Delta/\epsilon$	$2\Delta/\epsilon$
Reset ρ after each output of \top	No	Yes	No	No	No	No
Scale of query noise ν_i	$4c\Delta/\epsilon$	$4c\Delta/\epsilon$	$2c\Delta/\epsilon$	$4\Delta/3\epsilon$	0	$2\Delta/\epsilon$
Outputting $q_i + \nu_i$ instead of \top	No	No	Yes	No	No	No
Stop after outputting c ⊤'s	Yes	Yes	Yes	Yes	No	No
Privacy Property	e-DP	e-DP	∞-DP **	$\left(\frac{1+6\epsilon}{4}\epsilon\right)$ -DP	∞-DP	∞-DP

Figure 2: Differences among Algorithms 116.

— Lyu, Su, Dong

Use approximate coupling view of privacy to extend the logic apRHL

Combine smaller, pointwise proofs to prove differential privacy in apRHL

Get new, much simpler proofs using coupling composition principle

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(Also, I might be looking for a job ...)